

Seismic imaging with the elliptic Radon transform

Andreas Rieder

Christine Grathwohl

Peer Kunstmann

Todd Quinto

FAKULTÄT FÜR MATHEMATIK – INSTITUT FÜR ANGEWANDTE UND NUMERISCHE MATHEMATIK



Organization of the material



A linear inverse problem in seismic imaging The elliptic Radon transform Imaging operators: general results Imaging operators: concrete setting Numerical examples



A linear inverse problem in ▷ seismic imaging

The elliptic Radon transform

Imaging operators: general results

Imaging operators: concrete setting

Numerical examples

A linear inverse problem in seismic imaging

An inverse problem for the acoustic wave equation



 $u(t; \mathbf{x}, \mathbf{x_s})$ acoustic potential in $\mathbf{x} \in \mathbb{R}^d$, $d \in \{2, 3\}$, at time $t \ge 0$

$$\frac{1}{\nu^2}\partial_t^2 u - \Delta_{\mathbf{x}} u = \delta(\mathbf{x} - \mathbf{x}_{\mathbf{s}})\delta(t), \quad u(0, \cdot, \mathbf{x}_{\mathbf{s}}) = \partial_t u(0, \cdot, \mathbf{x}_{\mathbf{s}}) = 0,$$

 $\nu = \nu(\mathbf{x})$ speed of sound, $\mathbf{x_s}$ excitation (source) point.

Seismic imaging

Recover ν from the backscattered (reflected) fields

$$u(t; \mathbf{x}_{\mathbf{r}}, \mathbf{x}_{\mathbf{s}}), \quad t \in [0, T], \quad (\mathbf{x}_{\mathbf{r}}, \mathbf{x}_{\mathbf{s}}) \in \mathcal{R} \times \mathcal{S}$$

where

 \mathbb{S}/\mathbb{R} sets of source/receiver points, and

T observation period.

Generalized Radon transform



Consider the ansatz

$$\frac{1}{\nu^2(\mathbf{x})} = \frac{1+n(\mathbf{x})}{c^2(\mathbf{x})},$$

 $c = c(\mathbf{x})$ smooth and known background velocity. Determine *n* from (e.g. SYMES 1998)

$$Fn(T; \mathbf{x_r}, \mathbf{x_s}) \approx \int_0^T (T-t)^{d-2} (u - \widetilde{u})(t; \mathbf{x_r}, \mathbf{x_s}) dt$$

with the generalized Radon transform

$$Fw(T; \mathbf{x}_{\mathbf{r}}, \mathbf{x}_{\mathbf{s}}) = \int \frac{w(\mathbf{x})}{c^{2}(\mathbf{x})} a(\mathbf{x}, \mathbf{x}_{\mathbf{s}}) a(\mathbf{x}, \mathbf{x}_{\mathbf{r}}) \delta(T - \boldsymbol{\tau}(\mathbf{x}, \mathbf{x}_{\mathbf{s}}) - \boldsymbol{\tau}(\mathbf{x}, \mathbf{x}_{\mathbf{r}})) d\mathbf{x}$$

which integrates w over reflection isochrones: $T = \tau(\cdot, \mathbf{x_s}) + \tau(\cdot, \mathbf{x_r})$. Travel-time τ and amplitude a can be computed from

$$|\nabla_{\mathbf{x}} \boldsymbol{\tau}| = c^{-1}$$
 and $2\nabla_{\mathbf{x}} \boldsymbol{a} \cdot \nabla_{\mathbf{x}} \boldsymbol{\tau} + \boldsymbol{a} \Delta_{\mathbf{x}} \boldsymbol{\tau} = 0.$

Historical note: Kirchhoff migration



- Since the 1950's Kirchhoff migration is the standard technique to approximately solve the integral equation.
- BEYLKIN (1984, 1985) gave Kirchhoff migration a mathematical foundation:

 $n_{\text{rec}} = F^{\#} P g$ where g = F n are the data (measurements)

P convolution, $F^{\#}$ dual transform (generalized backprojection). Further,

$$n_{\rm rec} = F^{\#} P F n = I_{\rm partial} n + \Psi n,$$

 I_{partial} kind of band pass filter, Ψ is smoothing.

Our approach: complementing Kirchhoff



► As we cannot hope to recover n from the data completely we consider imaging operators which differ from the Kirchhoff operator $F^{\#}PF$:

$$\Lambda = K F^{\dagger} \psi F$$

- $\psi~$ smooth cutoff,
- F^{\dagger} (weighted) L^2 dual,
- K properly supported pseudo of positive order m.
- ▶ We reconstruct Λn from the data g = Fn.
- We compute the symbol of Λ to find useful K's.
- Our reconstruction technique based on Λ differs from Kirchhoff migration. In fact, an explicit expression of F^{\dagger} is not required (GRATHWOHL ET AL. 2018)



A linear inverse problem in seismic imaging

The elliptic ▷ Radon transform

Imaging operators: general results

Imaging operators: concrete setting

Numerical examples

The elliptic Radon transform

Assumptions



- Let d = 2 (for the ease of presentation). Further, let
- ▶ the background velocity c be constant, say, c = 1,
- ▶ $n \in L^2(\mathbb{R}^2_+)$ be compactly supported (the positive direction of the x_2 -axis points downwards),
- sources and receivers be parameterized by $s \in \mathbb{R}$ via

$$\mathbf{x}_{\mathbf{s}}(s) = (s - \alpha, 0)^{\top}, \qquad \mathbf{x}_{\mathbf{r}}(s) = (s + \alpha, 0)^{\top}.$$

with common offset $\alpha \ge 0$ (*common offset data acquisition geometry*).

Thus the reflection isochrones are ellipses with foci x_s and x_r .

The 2D situation







The elliptic Radon transform

Now the generalized RT becomes

$$Fw(s,t) = \int A(s,\mathbf{x})w(\mathbf{x})\delta(t-\varphi(s,\mathbf{x}))d\mathbf{x}, \quad t > 2\alpha,$$

with

$$\varphi(s, \mathbf{x}) := |\mathbf{x}_{\mathbf{s}}(s) - \mathbf{x}| + |\mathbf{x}_{\mathbf{r}}(s) - \mathbf{x}|$$

and

$$A(s, \mathbf{x}) = \frac{1}{\sqrt{|\mathbf{x}_{\mathbf{s}}(s) - \mathbf{x}| |\mathbf{x}_{\mathbf{r}}(s) - \mathbf{x}|}}.$$



A linear inverse problem in seismic imaging

The elliptic Radon transform

Imaging operators: general ▷ results

Imaging operators: concrete setting

Numerical examples

Imaging operators: general results

Karlsruher Institut für Technologie

Basics on pseudo-differential operators 1

Let $\Omega \subset \mathbb{R}^d$ be open and let $P \colon \mathcal{C}^{\infty}(\Omega) \to \mathcal{C}^{\infty}(\Omega)$ be a linear differential operator of order m,

$$Pu(\mathbf{x}) = \sum_{|\alpha| \le m} f_{\alpha}(\mathbf{x}) \partial^{\alpha} u(\mathbf{x}), \quad f_{\alpha} \in \mathbb{C}^{\infty}(\Omega).$$

If $u \in \mathfrak{C}^\infty_0(\Omega)$ then

$$Pu(\mathbf{x}) = \frac{1}{(2\pi)^{d/2}} \int e^{i \, \mathbf{x} \cdot \xi} p(\mathbf{x}, \xi) \widehat{u}(\xi) d\xi = \frac{1}{(2\pi)^d} \iint e^{i \, (\mathbf{x} - \mathbf{y}) \cdot \xi} p(\mathbf{x}, \xi) u(\mathbf{y}) d\mathbf{y} d\xi$$

where

$$p(\mathbf{x},\xi) = \sum_{|\alpha| \le m} f_{\alpha}(\mathbf{x})(\imath\xi)^{\alpha}$$

is the symbol of P.

Basics on pseudo-differential operators 2



► $p \in C^{\infty}(\Omega \times \mathbb{R}^d)$ is a **symbol** of order $m \in \mathbb{R}$ if for any $\alpha, \beta \in \mathbb{N}_0^d$ and any $K \Subset \Omega$ there is a $C = C_{\alpha,\beta,K}$ such that

$$\sup_{\mathbf{x}\in K} |\partial_x^{\alpha} \partial_{\xi}^{\beta} p(\mathbf{x},\xi)| \le C \left(1+|\xi|\right)^{m-|\beta|} \quad \text{for all } \xi \in \mathbb{R}^d.$$

- ► The set of all symbols of order m on Ω is denoted by $S^m(\Omega)$.
- For $p \in S^m(\Omega)$ we define the operator Ψ_p on $\mathcal{C}^\infty_0(\Omega)$ by

$$\Psi_p u(\mathbf{x}) = \frac{1}{(2\pi)^d} \iint e^{i (\mathbf{x} - \mathbf{y}) \cdot \xi} p(\mathbf{x}, \xi) u(\mathbf{y}) d\mathbf{y} d\xi$$

and call it a **pseudo-differential operator** of order m.

• The top order symbol $\sigma(\Psi_p)$ of Ψ_p is the equivalence class of p in $S^m(\Omega)/S^{m-1}(\Omega)$.

Basics on pseudo-differential operators 3



► Let P be the differential operator with symbol $\sum_{|\alpha| < m} f_{\alpha}(\mathbf{x})(\imath \xi)^{\alpha}$. Then,

$$\sigma(P) = \sum_{|\alpha|=m} f_{\alpha}(\mathbf{x})(\imath\xi)^{\alpha}.$$

► The operator $\Lambda^s = (I - \Delta)^{s/2}$ with symbol $(1 + |\xi|^2)^{s/2}$ of order $s \in \mathbb{R}$ has top order symbol

 $\varphi(\xi)|\xi|^s$

for any $\varphi \in \mathbb{C}^{\infty}$ with $\varphi(\xi) = 1$ for large $|\xi|$ where, in case of s < 0, we additionally require that $\varphi = 0$ in a neighborhood of 0.

Basics on pseudo-differential operators 4



Theorem: Let Ψ_p be a pseudo of order m. Then, $\Psi_p: H_0^s(\Omega) \to H_{loc}^{s-m}(\Omega)$ continuously¹ for all $s \in \mathbb{R}$.

Proof: See standard textbooks.

¹Topology of H_{loc}^s : $u_k \to u$ in H_{loc}^s if $\|\varphi u_k - \varphi u\|_s \to 0$ for all $\varphi \in \mathcal{C}_0^\infty(\Omega)$.

Setting the stage: the imaging operators



We consider

 $KF^{\dagger}\psi F$

where

▶ $\psi: S \times (2\alpha, \infty) \rightarrow [0, \infty)$ is a smooth compactly supported cutoff fct,

 \blacktriangleright F^{\dagger} is the *generalized backprojection* operator

$$F^{\dagger}u(\mathbf{x}) = \int_{S} W(s, \mathbf{x})u(s, \varphi(s, \mathbf{x})) \mathrm{d}s$$

where W is a smooth positive weight, and

 \triangleright K is a pseudo on \mathbb{R}^2_+ of pos. order m with symbol k (properly supp).

Here, S is the bounded open set of parameters $s \in \mathbb{R}$ for the source-receiver pairs.



Theorem: Let F, F^{\dagger} , K, ψ , and W be defined as above. Then,

$KF^{\dagger}\psi F$

is a pseudo of order m-1.

Proof:

- GUILLEMIN-STERNBERG 1977: Let R be any hypersurface Radon transform in a d-dim. space and let R^{\dagger} be its (formal, smoothly weighted) L^2 -adjoint. If R satisfies the Bolker assumption then $R^{\dagger}\psi R$ is a pseudo of order 1 d.
- Our transform F on \mathbb{R}^2_+ satisfies the Bolker assumption (KRISHNAN ET AL. 2012).
- ► Hence, $F^{\dagger}\psi F$ is a pseudo of order -1.
- \blacktriangleright K is properly supported and has order m.

The symbol



Theorem: The top order symbol of $KF^{\dagger}\psi F$ is

$$\sigma(\mathbf{x},\xi) = \frac{2\pi k(\mathbf{x},\xi)\psi(s,\varphi(s,\mathbf{x}))W(s,\mathbf{x})A(s,\mathbf{x})}{|\omega|B(s,\mathbf{x})}$$

where

$$B(s, \mathbf{x}) = \left| \det \begin{pmatrix} \nabla_x \varphi(s, \mathbf{x}) \\ \frac{\partial}{\partial s} \nabla_x \varphi(s, \mathbf{x}) \end{pmatrix} \right|$$

The symbol is evaluated at (\mathbf{x},ξ) where $s\in\mathbb{R}$ and $\omega\in\mathbb{R}$ are defined by

$$\xi = \omega \nabla_{\mathbf{x}} \varphi(s, \mathbf{x}).$$

$$\varphi(s, \mathbf{x}) = |\mathbf{x}_{\mathbf{s}}(s) - \mathbf{x}| + |\mathbf{x}_{\mathbf{r}}(s) - \mathbf{x}|, \quad A(s, \mathbf{x}) = \frac{1}{\sqrt{|\mathbf{x}_{\mathbf{s}}(s) - \mathbf{x}| |\mathbf{x}_{\mathbf{r}}(s) - \mathbf{x}|}}$$

The symbol



Theorem: The top order symbol of $KF^{\dagger}\psi F$ is

$$\sigma(\mathbf{x},\xi) = \frac{2\pi k(\mathbf{x},\xi)\psi(s,\varphi(s,\mathbf{x}))W(s,\mathbf{x})A(s,\mathbf{x})}{|\omega|B(s,\mathbf{x})}$$

where

$$B(s, \mathbf{x}) = \left| \det \begin{pmatrix} \nabla_x \varphi(s, \mathbf{x}) \\ \frac{\partial}{\partial s} \nabla_x \varphi(s, \mathbf{x}) \end{pmatrix} \right|$$

The symbol is evaluated at (\mathbf{x}, ξ) where $s \in \mathbb{R}$ and $\omega \in \mathbb{R}$ are defined by

 $\xi = \omega \nabla_{\mathbf{x}} \varphi(s, \mathbf{x}).$



Idea of the proof and related work



Follow the general calculation of QUINTO 1980: He expressed the symbol of generalized Radon transforms in terms of defining measures.

Microlocal properties of F and $F^*\psi F$ in various geometric settings have been studied by several authors, for instance,

BEYLKIN 1985, RAKESH 1988, NOLAN/SYMES 1997, TEN KRODE ET AL. 1998, STOLK 2000, DE HOOP ET AL. 2009, QUINTO ET AL. 2011, KRISHNAN ET AL. 2012, FELEA ET AL. 2016, ... etc.



A linear inverse problem in seismic imaging

The elliptic Radon transform

Imaging operators: general results

Imaging operators: concrete ▷ setting

Numerical examples

Imaging operators: concrete setting

The symbol: a closer look



Set

$$\Lambda := \Delta F^* \psi F,$$

that is, Λ has order 1 (cf. BLEISTEIN 1987).

Corollary: Let $\alpha = 0$. Then,

$$\sigma(\mathbf{x},\xi) = -\pi \, \frac{|\xi|}{x_2} \, \psi\Big(x_1 - \frac{\xi_1}{\xi_2} \, x_2, 2x_2 \frac{|\xi|}{|\xi_2|}\Big).$$

The symbol: a closer look



Set

$$\Lambda := \Delta F^* \psi F,$$

that is, Λ has order 1 (cf. BLEISTEIN 1987).

Corollary: Let $\alpha = 0$. Then,

$$\sigma(\mathbf{x},\xi) = -\pi \, \frac{|\xi|}{x_2} \, \psi\Big(x_1 - \frac{\xi_1}{\xi_2} \, x_2, 2x_2 \frac{|\xi|}{|\xi_2|}\Big).$$

$$C(\mathbf{x}) := \left\{ \xi \in \mathbb{R}^2 : \xi_2 \neq 0, \ \psi \left(x_1 - \frac{\xi_1}{\xi_2} x_2, 2x_2 \frac{|\xi|}{|\xi_2|} \right) > 0 \right\}.$$

Corollary: Let $\alpha = 0$ and $\xi \in C(\mathbf{x})$ for $\mathbf{x} \in \mathbb{R}^2_+$. Then, for $u \in \mathcal{D}'_0(\mathbb{R}^2_+)$ $(\mathbf{x}, \xi) \in \mathrm{WF}^s(u) \iff (\mathbf{x}, \xi) \in \mathrm{WF}^{s-1}(\Lambda u).$

 $(\mathbf{x},\xi) \in WF^{s}(u) \iff u$ fails to be in H^{s} about \mathbf{x} in direction ξ

The symbol: a closer look



Set

$$\Lambda := \Delta F^* \psi F,$$

that is, Λ has order 1 (cf. BLEISTEIN 1987).

Corollary: Let $\alpha = 0$. Then,

$$\sigma(\mathbf{x},\xi) = -\pi \, \frac{|\xi|}{x_2} \, \psi\Big(x_1 - \frac{\xi_1}{\xi_2} \, x_2, 2x_2 \frac{|\xi|}{|\xi_2|}\Big).$$

$$C(\mathbf{x}) := \left\{ \xi \in \mathbb{R}^2 : \xi_2 \neq 0, \ \psi \left(x_1 - \frac{\xi_1}{\xi_2} x_2, 2x_2 \frac{|\xi|}{|\xi_2|} \right) > 0 \right\}.$$

Corollary: Let $\alpha = 0$ and $\xi \in C(\mathbf{x})$ for $\mathbf{x} \in \mathbb{R}^2_+$. Then, for $u \in \mathcal{D}'_0(\mathbb{R}^2_+)$ $(\mathbf{x}, \xi) \in WF^s(u) \iff (\mathbf{x}, \xi) \in WF^{s-1}(\Lambda u).$

Remark: Similar results hold for $\alpha > 0$.



H^s-Wavefront set: an example

Let $\Omega \subset \mathbb{R}^d$ be open with a \mathcal{C}^{∞} -boundary. Then

WF^s(χ_{Ω}) = {(\mathbf{x}, ξ) : $\mathbf{x} \in bd(\Omega), \xi \in \mathbb{R}^d \setminus \{\mathbf{0}\}, \xi \perp bd(\Omega) \text{ at } \mathbf{x}\}, s \ge 1/2.$

For s < 1/2 we have $WF^s(\chi_{\Omega}) = \emptyset$.





The symbol for $\alpha > 0$

$$\sigma(\mathbf{x},\xi) \approx -\pi \, \frac{|\xi|}{x_2} \, \psi \Big(x_1 - \frac{\xi_1}{\xi_2} \, x_2, 2x_2 \frac{|\xi|}{|\xi_2|} \Big) \quad \text{for } x_2 \gg \alpha$$

$$\sigma(\mathbf{x},\xi) \approx -\frac{\pi}{2} \, \frac{|\xi|^4}{|\xi_2| \, |\xi_1|^2} \, \frac{1}{\alpha} \, \psi\Big(x_1 - \alpha, 2\alpha + x_2 \, \frac{|\xi|^2}{2|\xi_1\xi_2|}\Big) \quad \text{for } \alpha \gg x_2$$

Modified imaging operator



 $\Lambda_{\mathrm{mod}} := \Delta (M + \alpha I) F_2^* \psi F_2$

where M is multiplication with x_2 .

The top order symbol of Λ_{mod} is $(x_2 + \alpha)\sigma(\mathbf{x}, \xi)$.

- The symbol of Λ_{mod} compensates the factor $1/x_2$ for $x_2 \gg \alpha$ and $1/\alpha$ for $\alpha \gg x_2$.
- Thus, jumps in n with the same height but at different depths will be reconstructed with the same intensities relatively independent of α .



A linear inverse problem in seismic imaging

The elliptic Radon transform

Imaging operators: general results

Imaging operators: concrete setting

Numerical ▷ examples

Numerical examples

The phantom n and its transform ψFn







 Λ vs. Λ_{mod} for $\alpha=1$





Λ vs. Λ_{mod} for $\alpha=10$





Data from the wave equation

$$Fw(T; \mathbf{x}_{\mathbf{r}}, \mathbf{x}_{\mathbf{s}}) = \int_{0}^{T} (u - \widetilde{u})(t; \mathbf{x}_{\mathbf{r}}, \mathbf{x}_{\mathbf{s}}) dt$$



▶ $[0.1,1] \times [0.1,0.8]$ with absorbing bc using PML. Step size 0.01.

- ▶ 17 source/receiver pairs, $\alpha = 0.05$, positioned at $(s \pm \alpha, 0.1)$, $s \in \{0.15 + 0.05i : i = 0, ..., 16\}$, to record u at the receivers.
- Temporal source signal: scaled Gaussian.
 - \widetilde{u} was computed with constant sound speed c = 1.

Wavefields



Cosine profile

PySIT –Seismic Imaging Toolbox for Python

by L. Demanet & R. Hewitt

Sine profile

Preprocessed seismograms





$$y(s,t) = \int_0^T (u - \widetilde{u})(t; \mathbf{x}_r(s), \mathbf{x}_s(s)) dt$$

Reconstructed images







Wrong background velocity





Things to remember

- We introduced a class of imaging operators for the elliptic Radon transform for enhancing singularities.
- These operators are pseudo-differential operators and we computed their symbols explicitly.
- Thus, we constructed operators which reconstruct relatively independently of depth and offset.



Things to remember

- We introduced a class of imaging operators for the elliptic Radon transform for enhancing singularities.
- These operators are pseudo-differential operators and we computed their symbols explicitly.
- Thus, we constructed operators which reconstruct relatively independently of depth and offset.

Next challenges

Non-constant background velocity: symbol, inversion scheme, field data.



Things to remember

- We introduced a class of imaging operators for the elliptic Radon transform for enhancing singularities.
- These operators are pseudo-differential operators and we computed their symbols explicitly.
- Thus, we constructed operators which reconstruct relatively independently of depth and offset.

Next challenges

Non-constant background velocity: symbol, inversion scheme, field data.

Thank you for your attention!



Approximate inverse²

Instead of $\Lambda n(\mathbf{p})$ we try to compute

$$\Lambda_{\gamma} n(\mathbf{p}) := \langle \Lambda n, e_{\mathbf{p}, \gamma} \rangle_{L^2(\mathbb{R}^2)} = \Lambda n \star e_{\mathbf{0}, \gamma}(\mathbf{p})$$

where $e_{\mathbf{p},\gamma}$, $\gamma > 0$, is a mollifier:

$$\operatorname{supp} e_{\mathbf{p},\gamma} = \overline{B_{\gamma}(\mathbf{p})}, \qquad \int e_{\mathbf{p},\gamma}(\mathbf{x}) \mathrm{d}\mathbf{x} = 1, \qquad e_{\mathbf{p},\gamma} \xrightarrow{\gamma \to 0} \delta(\cdot - \mathbf{p}).$$

We use

$$e_{\mathbf{p},\gamma,k}(\mathbf{x}) = C_{k,\gamma} \begin{cases} (\gamma^2 - \Theta^2)^k : \Theta < \gamma, \\ 0 : \Theta \ge \gamma, \end{cases} \quad \Theta = |\mathbf{x} - \mathbf{p}|,$$

with k > 0 and

$$C_{k,\gamma} = \frac{k+1}{\pi \gamma^{2(k+1)}}.$$

²Louis 1996

Reconstruction kernel



Lemma: For $k \geq 3$ we have that $\Lambda_{\gamma} n(\mathbf{p}) = \langle \Phi F n, \psi_{\mathbf{p},\gamma,k} \rangle_{L^2(\mathbb{R} \times]2\alpha,\infty[)}$ with the *reconstruction kernel* $\psi_{\mathbf{p},\gamma,k}(s,t) = 4k C_{k,\gamma} \Big((k-1) F \Big(|\cdot -\mathbf{p}|^2 \widetilde{e}_{\mathbf{p},\gamma,k-2} \Big)(s,t) - F \widetilde{e}_{\mathbf{p},\gamma,k-1}(s,t) \Big)$ with $\widetilde{e}_{\mathbf{p},\gamma,k} = e_{\mathbf{p},\gamma,k}/C_{k,\gamma}$. **Proof:** By duality, $\Lambda_{\gamma}n(\mathbf{p}) = \langle \Delta F^* \Phi Fn, e_{\mathbf{p},\gamma,k} \rangle = \langle \Phi Fn, \psi_{\mathbf{p},\gamma,k} \rangle$ with $\psi_{\mathbf{p},\gamma,k} = F\Delta e_{\mathbf{p},\gamma,k} = C_{k,\gamma}F\Delta \widetilde{e}_{\mathbf{p},\gamma,k}$

and $\Delta \widetilde{e}_{\mathbf{p},\gamma,k} = 4k(k-1) |\cdot -\mathbf{p}|^2 \widetilde{e}_{\mathbf{p},\gamma,k-2} - 4k \widetilde{e}_{\mathbf{p},\gamma,k-1}$ yields the result. \checkmark

The kernel for $\boldsymbol{\Lambda}$





Discretization



We compute

$$\Lambda_{\gamma} n(\mathbf{p}) = \langle \Phi F n, \psi_{\mathbf{p},\gamma,3} \rangle_{L^2(\mathbb{R} \times]2\alpha,\infty[)}$$

from the discrete data

$$g(i,j) = \Phi(s_i, t_j) Fn(s_i, t_j), \quad i = 1, \dots, N_s, \ j = 1, \dots, N_t,$$

where

 $\{s_i\} \subset [-s_{\max}, s_{\max}]$ and $\{t_j\} \subset [t_{\min}, t_{\max}], t_{\min} > 2\alpha$,

are uniformly distributed with step sizes h_s and h_t , respectively.

$$\Lambda_{\gamma} n(\mathbf{p}) \approx \widetilde{\Lambda}_{\gamma} n(\mathbf{p}) := h_s h_t \sum_{i=1}^{N_s} \sum_{t_j \in \mathcal{T}_i(\mathbf{p})} g(i,j) \,\psi_{\mathbf{p},\gamma,3}(s_i,t_j)$$

with $|\mathfrak{T}_i(\mathbf{p})| \sim \gamma$.



Computing the kernel

Let χ be the indicator function of $B_r(\mathbf{p})$ which is in the lower half-space. To evaluate

$$F\chi(s,t) = \int A(s,\mathbf{x})\chi(\mathbf{x})\delta(t-\varphi(s,\mathbf{x}))d\mathbf{x}, \quad t>2\alpha,$$

we transform the integral by elliptic coordinates $\mathbf{x}(s,t,\phi) = (x_1,x_2)^{\top}$,

$$x_1 = s + \frac{t}{2}\cos\phi$$
 and $x_2 = \sqrt{\frac{t^2}{4} - \alpha^2}\sin\phi$.

Note: $E(s,t) = \{\mathbf{x}(s,t,\phi) : \phi \in [0,2\pi]\}$ ellipse wrt $\mathbf{x}_{\mathbf{s}}(s)$, $\mathbf{x}_{\mathbf{r}}(s)$, and t.

Thus,

$$F\chi(s,t) = \frac{1}{\sqrt{t^2 - 4\alpha^2}} \int_0^\pi \chi(\mathbf{x}(s,t,\phi)) \,\mathrm{d}\phi.$$



To evaluate $F\chi(s,t)$ further we provide the following quantities

$$T_{-/+} = T_{-/+}(s, r, \mathbf{p}) = \min / \max \big\{ \varphi(s, \mathbf{x}) : \mathbf{x} \in \partial B_r(\mathbf{p}) \big\}.$$



 $E(s,t) \cap B_r(\mathbf{p}) \neq \emptyset \iff T_- < t < T_+$ For $t \in]T_-, T_+[$: $E(s,t) \cap B_r(\mathbf{p}) = \{\mathbf{x}(s,t,\phi) : \phi \in [\phi_1,\phi_2]\}$

$$F\chi(s,t) = \begin{cases} 0 & : t \notin]T_{-}, T_{+}[\\ \frac{\phi_{2} - \phi_{1}}{\sqrt{t^{2} - 4\alpha^{2}}} & : t \in]T_{-}, T_{+}[\end{cases}$$



Remaining tasks: Compute $T_{-/+}$, $\phi_{1/2}$.

$$T_{-/+} = \min / \max \left\{ \widetilde{\varphi}(\vartheta) : \vartheta \in [0, 2\pi[\right\}$$

where

$$\widetilde{\varphi}(\vartheta) := \varphi(s, \mathbf{p} + r(\cos\vartheta, \sin\vartheta)^{\top}).$$

- $\triangleright \widetilde{\varphi}$ attains exactly one minimum and one maximum in $[0, 2\pi]$.
- ► As both extrema are clearly separated, we can apply Newton's method to get the two zeros of $\tilde{\varphi}'$.



• Having T_{\mp} we solve

$$r^2 = |\mathbf{p} - \mathbf{x}(s, t, \phi)|^2$$
 for ϕ .

For $t \in]T_-, T_+[$, $s \in \mathbb{R}$ we have exactly the two solutions ϕ_1 and ϕ_2 .

We substitute

$$z = \cos \phi, \qquad b = (s - p_1) t,$$

$$c = (p_1 - s)^2 + p_2^2 + \frac{t^2}{4} - \alpha^2 - r^2, \qquad d = \sqrt{t^2 - 4\alpha^2} p_2,$$

to obtain the equation

$$d\sqrt{1-z^2} = c + bz + \alpha^2 z^2$$

which has exactly two solutions $-1 \le z_2 < z_1 \le 1$.

► By Newton's method again,

$$\phi_i = \arccos z_i, \quad i = 1, 2.$$



- ► The kernel $\psi_{\mathbf{p},\gamma,k} = F\Delta e_{\mathbf{p},\gamma,k}$ can be computed just as $F\chi$.
- lndeed, let k = 3, then

$$\Delta e_{\mathbf{p},\gamma,3}(\mathbf{x}) = C_{3,\gamma} \left(-36 \, |\mathbf{x} - \mathbf{p}|^4 + 48\gamma^2 \, |\mathbf{x} - \mathbf{p}|^2 - 12\gamma^4 \right) \chi_{B_{\gamma}(\mathbf{p})}(\mathbf{x}).$$

Now F can be applied to each of the components of $\Delta e_{\mathbf{p},\gamma,3}$, e.g.,

$$F(|\cdot -\mathbf{p}|^{4}\chi_{B_{\gamma}(\mathbf{p})})(s,t) = \begin{cases} 0 & : t \notin]T_{-}, T_{+}[, \\ \frac{1}{\sqrt{t^{2} - 4\alpha^{2}}} \int_{\phi_{1}}^{\phi_{2}} |\mathbf{x}(s,t,\phi) - \mathbf{p}|^{4} \, \mathrm{d}\phi : t \in]T_{-}, T_{+}[.$$

Here,

$$|\mathbf{x}(s,t,\phi) - \mathbf{p}|^4 = \left(\left(s - p_1 + \frac{t}{2}\cos\phi\right)^2 + \left(\sqrt{\frac{t^2}{4} - \alpha^2}\sin\phi - p_2\right)^2 \right)^2$$

is a trigonometric polynomial which can be integrated analytically.